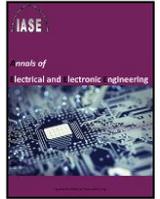




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## Genetic algorithm based optimization method for reactive power management



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### ABSTRACT

Reactive power management is a complicated and nonlinear problem. With the development of computer-based methods, some new methods have been proposed for this problem. The nature-based optimization algorithms are an efficient way of solving the nonlinear and not differentiable functions. One of the interesting of these algorithms is a genetic algorithm or GA. In this study, we proposed the application of a genetic algorithm for solving reactive power optimization. The proposed method must find the best parameters of power network including the generator node voltage, the transformers tap situation, and the parallel compensators value. In existing electrical power networks, these variables don't consider and all capacity of the system didn't use. In the traditional power network, the voltage profile is weak and the active power loss in transmission lines is high. With optimizing the reactive power control parameters, the voltage profile improved and the active power loss will be reduced significantly. In order to test the proposed system, the IEEE standard 25-node network is chosen. The simulation results show that the proposed method has a good effect on system performance.

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### 1. Introduction

In modern electrical power network many problem merged such as weak voltage profile, active power loss in transmission lines, low power factor. These problems can be removed or modified by reactive power compensation. There are many different methods and techniques for reactive power compensation. The first one is capacitor placement in different nodes of electrical power network. In last year's many intelligent approaches have been proposed for optimal capacitor placement in power network. These methods are based on nature based optimization algorithm (Lee et al., 2015; Vuletić and Todorovski, 2014; Shuaib et al., 2015; Mukherjee and Goswami, 2014; Elsheikh et al., 2014; Sultana and Roy, 2014). The second method is FACTS devices that introduced in 1980s. There are several FACTS devices such as SVC, STATCOM and UPFC. In last year's many techniques based on FACTS devices are introduced for system quality improvement. Also many control system have been proposed to control these devices (Sreejith et al., 2015; Balamurugan et al., 2015; Dash et al., 2015; Gasperic and Mihalic, 2015; Castoldi et al., 2014; Kumar and Mittapalli, 2014).

The mentioned methods to reactive power control have some financial investment. These problems restrict the usage of these methods. The one efficient method to reactive power control is setting of reactive power control variables. The setting of reactive power control variables involve of tuning of synchronous generators voltage magnitude, the position of power transformers tap, the value of parallel capacitors, the value of inductors. In this problem the voltage of synchronous generators is continuous variable and the position of power transformers tap, the value of parallel capacitors, the value of inductors are discrete. The management of reactive power is very complicated

optimization problem. This problem has many limitation and variables that must be considered. All the variables have its special search space. Also the characters of each variable are special and are independent with other variables. For solving this nonlinear and complicated optimization problem, the powerful algorithm is needed.

With development in computer capability in computing and solving nonlinear problem, the solution of this problem is come easier. In last decades the nature based optimization algorithms are emerged such as genetic algorithm (GA), particle swarm optimization (PSO) algorithm, bee's algorithm (BA), imperialist competitive algorithm (ICA) and cuckoo optimization algorithm (COA) (Zhang et al., 2015; Yu et al., 2015; Gopalakrishnan and Kosanovic, 2015; Chen et al., 2015; Cheng and Jin, 2015; Li et al., 2015; Liu et al., 2015). One of the most efficient and powerful of these algorithms is genetic algorithm. This optimization algorithm has many applications in many areas of industrials and sciences (Quiroz-Castellanos et al., 2015; Anglada and Garmendia, 2015; Lu et al., 2015; Király and Abonyi, 2015; Duan et al., 2015; Wang et al., 2015; Changdar et al., 2015; Herath et al., 2015). In this paper an intelligent technique is proposed for reactive power variable setting. In each optimization algorithm to features are essential: exploration and extraction. The exploration feature is the capability of finding the global solution's vicinity. The extraction feature is capability of optimization algorithm to find the global solution from this vicinity. The genetic algorithm has good exploration and extraction capability. Therefore in this study exploration and extraction is selected as optimization algorithm.

Wu et al. (1998) suggested application of optimal reactive power dispatch by modified GA version for reactive power management. Varadarajan and Swarup (2008) introduced DE algorithm for best reactive power management. Zhang et al. (2010) have introduced multi-group self-adaptive DE algorithm for reactive power forecasting and management. Nedwick et al. (1995) have proposed an intelligent technique for reactive power optimization in power network. The proposed system uses fix

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capacitors in several nodes. Dong et al. (2005) have been introduced a smart approach to reactive power management by Bender's decomposition approach. Yang et al. (2007) constrained programming accounting uncertain factors is used to reactive power optimization. In this paper the power that generated by synchronous generators and the load consumed by final load modeled as distribution variables. In Wu et al. (2008); an intelligent technique based on OPF is proposed for reactive power management in heavy load power network condition. He et al. (2008) proposed the optimization method to reactive power prediction with considering the voltage profile. In Zhang et al. (2009) researchers proposed a computational system in order to reactive power market clearing. The simulation results show good performance.

In this paper an intelligent technique based on GA is proposed for reactive power prediction for next load condition. More details about the proposed method are described in next sections. The proposed method enhances the voltage profile significantly and reduces the active power loss. In the proposed method, reactive power is reserved to be used in emergency

situations. In the proposed method, the voltage based reactive power applied to compute the reactive power demand. The description about GA is come in section two. Section 3 presents the formulation of power system. Section 4 presents proposed method and some simulation results. The section 5 concludes the study.

## 2. Genetic algorithm

In soft computing science, genetic algorithm is an optimization algorithm that models the process of natural selection in animals and human. The genetic algorithm is used for many optimization problems that are very complicated and nonlinear. Also genetic algorithm can be used for discrete optimization problem. The genetic algorithm is one of the evolutionary algorithms (EA) that generate random solutions to optimization problems that this procedure is based on natural events in human or animal's life. The genetic algorithm has several main operators: elitism, crossover, mutation and roulette wheel. The flowchart of genetic algorithm is depicted in Fig. 1.

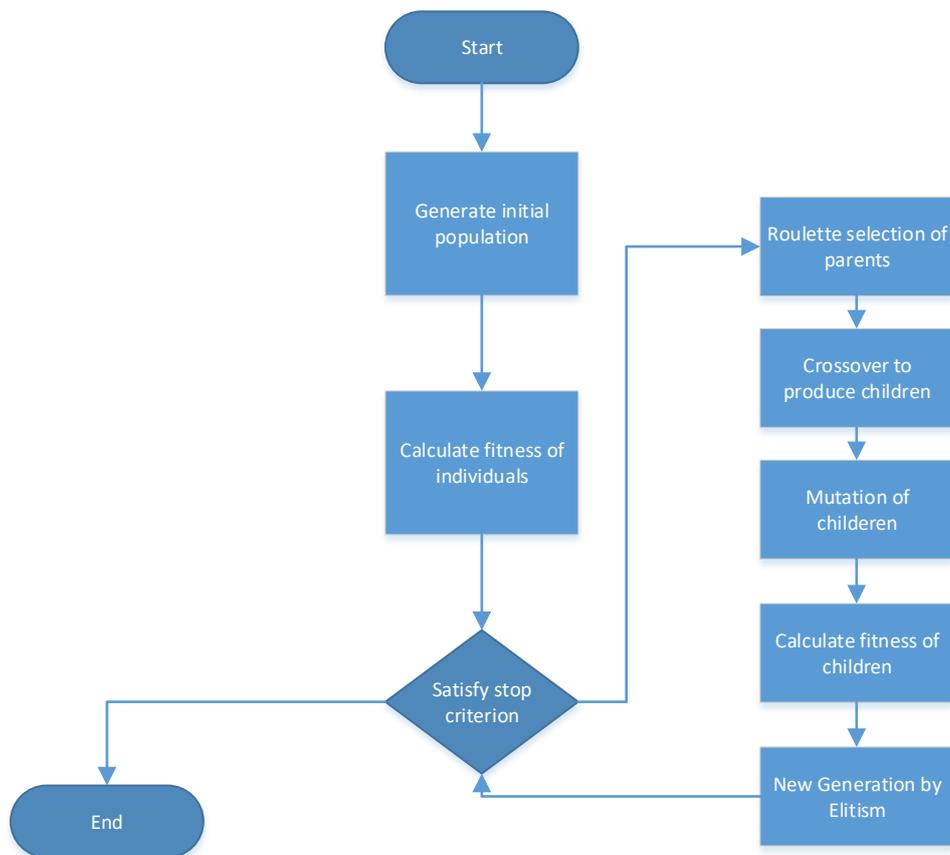


Fig. 1: GA flowchart

In the genetic algorithm like other nature based optimization algorithms, initial random population is generated. The each candidate in initial random population is called chromosome. These chromosomes are like particle in particle swarm optimization algorithm, bee in bee's algorithm or countries in imperialist competitive algorithm. The chromosomes must be generated in predetermined search space. The low boundary and maximum boundary of each problem is unique. The optimization process starts with initial random population, and in each iteration or generation, the fitness function is calculated. Based on the evaluated fitness function for each chromosome, the elitism and crossover is performed. The chromosomes with high level of fitness are randomly chosen from the existing population, and each chromosome is modified by crossover operator. The new generated population is used in following iteration. The same procedure is performed iteratively. In any iteration the

stopping criteria must be checked. If the stopping criteria are satisfied, the algorithm will stop the searching procedure. Fig. 2 shows the crossover operation. Also Fig. 3 shows the mutation operation. Fig. 4 shows the pseudo code of GA.

## 3. Problem formulation

In this paper reactive power reserve is investigated and new smart approach is proposed for this complicated and nonlinear problem. For this purpose GA is used. The GA is used to find the optimal parameters of reactive power control variables. The objective function of this optimization problem is as follow (Arya et al., 2010):

$$J = \sum_k p_{gk} (\bar{Q}_{gk} - Q_{qk}) \quad (1)$$

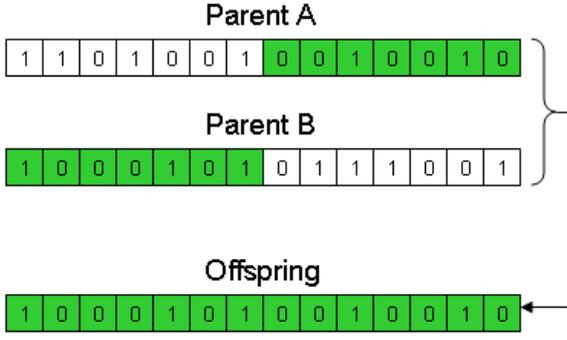


Fig. 2. Crossover operation.

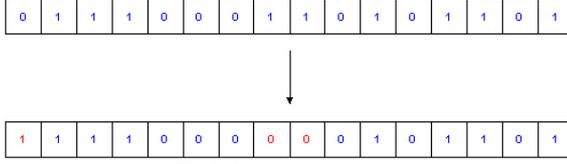


Fig. 3. Mutation operation.

```

0. GENERATE POPULATION P[0]
1. DO{
    1.1 EVALUATE FITNESS OF INDIVIDUALS IN P[k]
    1.2 DO{
        SELECTION (ROULETTE WHEEL)
        APPLY GENETIC OPERATORS:
            PMX CROSSOVER (PROBABILITY Pc)
            MUTATION (PROBABILITY Pm)
    }
    WHILE NEW GENERATION NOT COMPLETED
    1.3 EXECUTE CREATE-ELITE
}
WHILE {TERMINATION CRITERIA = NO}
2. PRINT BEST ASSIGNMENT SOLUTION ui

FUNCTION CREATE-ELITE:
{
    SELECTION OF BEST INDIVIDUALS
    MUTATION (PROBABILITY Pm)
    ELITE = MUTATED ELITE + NOT-MUTATED ELITE
    INSERT ELITE INTO POPULATION:
        P[k+1]=INSERT (ELITE, P[k])
}
    
```

Fig. 4. The pseudo code of GA algorithm.

In the fitness function, some limitations and constraints are considered. These limitations and constraints are described below:

(a) Power flow limitations and constraints. The mathematical formulation of this limitation is defined as follow:

$$\begin{aligned} \underline{P} &= f(\underline{V}, \delta) \\ \underline{Q} &= g(\underline{V}, \delta) \end{aligned} \quad (2)$$

(b) Limitation and relation of node voltages and next predicted load situation and the level of reactive power demand. Eq. 3 defines these conditions:

$$\begin{aligned} \underline{V}_i &\leq V_i^o \leq \overline{V}_i \\ \underline{V}_i &\leq V_i^p \leq \overline{V}_i \end{aligned} \quad (3)$$

$i \in \text{NL}$

(c) Limitation on Jacobin matrix and its related determinant.

$$\lambda_{\min,p} \geq \lambda_{\min,th} \quad (4)$$

(d) The boundaries of generated reactive power in power network. Eq. 5 shows this limitation.

$$\underline{Q}_{gk} \leq Q_{gkp} \leq \overline{Q}_{gk}, k = 1, 2, \dots, \text{NG} \quad (5)$$

(e) Limitation on control parameters:

$$\underline{X}_i \leq X_i \leq \overline{X}_i, i \in \text{NC} \quad (6)$$

In the proposed method,  $p_{gk}$  is generation association factor. This factor is calculated for next forecasting load condition. For this purpose first obtain minimum eigenvalues and their related vectors. For simplicity the reduced Jacobin matrix is applied. The procedure is as follow:

$$\begin{bmatrix} J_1 J_2 \\ J_3 J_4 \end{bmatrix} \begin{bmatrix} \Delta\delta \\ \Delta V \end{bmatrix} = \begin{bmatrix} 0 \\ \Delta Q \end{bmatrix} \quad (7)$$

$$\begin{aligned} J_1 \Delta\delta + J_2 \Delta V &= 0 \\ \Delta\delta &= -J_1^{-1} J_2 \Delta V \end{aligned} \quad (8)$$

$$\begin{bmatrix} J_4 - J_3 J_1^{-1} J_2 \end{bmatrix} \Delta V = \Delta Q \quad (9)$$

$$J_R = J_4 - J_3 J_1^{-1} J_2$$

$$\Delta Q = \begin{bmatrix} \xi_i \end{bmatrix}$$

$$\Delta V = \frac{\xi_i}{\lambda_i} \quad (10)$$

$$\Delta\delta = -J_1^{-1} J_2 \Delta V = -\frac{(J_1^{-1} J_2 \xi_i)}{\lambda_i}$$

$$V = V + \Delta V$$

$$\delta = \delta + \Delta\delta$$

In next step, the demanded reactive power that must be injected is computed as follow:

$$p_{gk} = \frac{\Delta Q_{gk}}{\max_p \Delta Q_{gp}} \quad (11)$$

The steps of proposed method are as follow:

1. The parameters of power network, including the reactive power parameters, transmission lines impedance, transformers power.
2. Compute the load flow for network. Compute all nodes voltage value and their angles.
3. Compute the following condition demanded power.
4. Compute the load flow calculation for next load condition.
5. Generate the initial population for optimization algorithm.
6. Evaluate the fitness function for generated random chromosomes.
7. Do elitism operation.
8. Apply crossover.
9. Apply mutation.
10. Check the stop criteria. If it is satisfied, go to next step, else go to step 6.
11. Finish.

#### 4. Simulation results

In this section the performance of proposed method is evaluated. For this purpose IEEE standard system is selected. The selected is power network system has 25 terminals. The chosen system has twelve parameters that can affect the generation of reactive power. In this system there are five generation terminal and the other remaining terminals are load nodes. The control parameters are voltages of generator terminals, parallel compensations and on line tap changeable transformers. The parallel compensations are placed at 22, 23, 24 and 25<sup>th</sup> terminal. The on line tap changeable transformers are located in 6, 13 and 35<sup>th</sup> transmission lines. The nominal values of voltages and

impedance of system are listed in Table 1. Also Table 2 shows the system constants. Table 3 shows the voltage boundaries.

**Table 1**  
Parameters and constants of power network.

Parameter	Value
$E_{max1}$	2.66pu
$E_{max2}$	2.17pu
$E_{max3}$	2.11pu
$E_{max4}$	2.32pu
$E_{max5}$	2.14pu
$X_{d1}$	1.00pu
$X_{d2}$	1.16pu
$X_{d3}$	1.08pu
$X_{d4}$	1.21pu
$X_{d5}$	1.13pu

**Table 2**  
System parameters.

Maximum value for reactive power	$\bar{Q}_{gk}$
Value of reactive power reserved	$Q_{gk(res)}$
The value of generator voltage	$V_g$
The generator voltage (internal voltage)	$\bar{E}$
Impedance of generator	$X_d$
armature current for generators	$\tilde{I}_{gk}$
The voltage in terminals	$V$
Phase	$\delta$
The number of optimization parameters	$NC$
The number of consuming terminals	$NL$
The number of nodes that generate active power	$NG$
Fitness function	$J$
Random number	$rand_j$
Factor	$\alpha$
Chancily number	$j_{rand}$
The boundaries	$x_i, \bar{x}_i$
Location of individual	$X_i^k$
Crossover rate	$C$
The maximum iteration	$NIT, NIT_{max}$
Best individual	$P_{best(i)}^k$
position of the best individual of the whole swarm	$P_{best}^k$

**Table 3**  
Voltage boundaries.

Node	Boundaries
PV-bus	0.95– 1.15 pu
Parallel capacitor	0.00–0.055 pu
On line tap changeable transformers	0.90–1.10 pu
First generator	-0.0500 pu to 3.0000 pu
Second generator	-0.0500 pu to 1.0000 pu
Third generator	-0.0500 pu to 1.0000 pu
Forth generator	-0.0500 pu to 1.0000 pu
Fifth generator	-0.0500 pu to 1.0000 pu

The other power system constants and parameters are as follow. The total active power is 15.731 pu and reactive power is 4.828 pu. The proximity indicator is 0.363 and the fitness function is 2.33. Table 4 shows the voltage of power network before optimization.

The obtained results after optimization are listed in Table 5. The parameters of GA have high effect on its performance. For this purpose several collection of these parameters are tested. Also in Fig. 5 the increasing of fitness function during the optimization is plotted. It is clear that the optimization has good effect on fitness function. Also Table 6 shows the optimized control variables.

**Table 4**  
Voltage before optimization.

Terminal voltages	Values (PU)	Control parameter	Values (PU)
$V_{n6}$	1.0061	$V_{G1}$	1.014
$V_{n7}$	1.0056	$V_{G2}$	1.093
$V_{n8}$	0.8521	$V_{G3}$	1.076
$V_{n9}$	0.8651	$V_{G4}$	1.054
$V_{n10}$	0.8654	$V_{G5}$	1.049
$V_{n11}$	0.9016	$B_{C,SH22}$	0.0241
$V_{n12}$	0.9351	$B_{C,SH23}$	0.0237
$V_{n13}$	0.8962	$B_{C,SH24}$	0.0231
$V_{n14}$	1.0667	$B_{C,SH25}$	0.0229
$V_{n15}$	0.8521	$TAP_{T6}$	0.9156
$V_{n16}$	0.8619	$TAP_{T13}$	0.9154
$V_{n17}$	0.8654	$TAP_{T35}$	0.9187
$V_{n18}$	0.9013		
$V_{n19}$	0.9336		
$V_{n20}$	0.8962		
$V_{n21}$	1.0667		
$V_{n22}$	0.8450		
$V_{n23}$	0.8642		
$V_{n24}$	0.9062		
$V_{n25}$	0.8641		

**Table 5**  
Obtained results after optimization.

Case	Crossover rate	Mutation rate	Fitness function
1	0.7	0.1	14.431
2	0.7	0.15	13.87
3	0.7	0.2	14.04
4	0.7	0.25	14.16
5	0.7	0.3	14.12
6	0.75	0.1	13.97
7	0.75	0.15	13.76
8	0.75	0.2	14.53
9	0.75	0.25	14.41
10	0.75	0.3	13.98
11	0.8	0.1	14.17
12	0.8	0.15	14.21
13	0.8	0.2	14.21
14	0.8	0.25	13.95
15	0.8	0.3	13.76
16	0.85	0.1	14.53
17	0.85	0.15	14.431
18	0.85	0.2	13.83
19	0.85	0.25	14.04
20	0.85	0.3	14.01
21	0.9	0.1	14.18
22	0.9	0.15	14.22
23	0.9	0.2	13.76
24	0.9	0.25	14.53
25	0.9	0.3	14.12
26	0.95	0.1	13.97
27	0.95	0.15	13.76
28	0.95	0.2	14.53
29	0.95	0.25	13.88
30	0.95	0.3	14.31

### 5. Conclusion

The power system is very complicated and nonlinear. There is no linear relation among different sections of this network. In this study an intelligent system proposed for reactive power optimal management. The proposed is based on GA. The computer simulation results show that the optimization has very high impact on power quality. After optimization, the voltage profile is enhanced significantly.

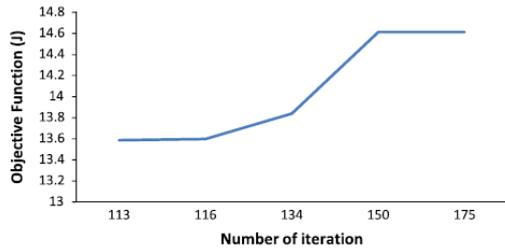


Fig. 5. Increasing of fitness function during optimization procedure.

Table 6  
Control parameters after optimization.

Terminal voltages	Values (PU)	Control parameter	Values (PU)
$V_{n6}$	1.0065	$V_{G1}$	1.094
$V_{n7}$	1.0051	$V_{G2}$	1.01
$V_{n8}$	1.0032	$V_{G3}$	1.02
$V_{n9}$	0.9976	$V_{G4}$	1.021
$V_{n10}$	1.0043	$V_{G5}$	1.026
$V_{n11}$	0.9965	$B_{C,SH22}$	0.0232
$V_{n12}$	0.9954	$B_{C,SH23}$	0.0269
$V_{n13}$	1.0021	$B_{C,SH24}$	0.0481
$V_{n14}$	1.0001	$B_{C,SH25}$	0.0375
$V_{n15}$	0.9934	$TAP_{T6}$	0.9201
$V_{n16}$	1.0043	$TAP_{T13}$	0.9219
$V_{n17}$	0.9962	$TAP_{T35}$	1.043
$V_{n18}$	0.9951		
$V_{n19}$	1.0087		
$V_{n20}$	1.0076		
$V_{n21}$	0.9995		
$V_{n22}$	1.0056		
$V_{n23}$	1.0003		
$V_{n24}$	1.0021		
$V_{n25}$	0.9959		

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